Exercise sheet 6

Exercise 6-1

The numbers quantifying the degree of industrialization $\tilde{\iota}$ of a society, its fertility rate \tilde{f} , and the stork population \tilde{s} on its territory are random variables assumed to belong to a joint threedimensional Gaussian distribution. Consider the fluctuations around the respective mean values $\iota = \tilde{\iota} - \langle \tilde{\iota} \rangle_{(\tilde{\iota})}, f = \tilde{f} - \langle \tilde{f} \rangle_{(\tilde{f})}, \text{ and } s = \tilde{s} - \langle \tilde{s} \rangle_{(\tilde{s})}$. It is known that both the stork index s and the fertility index f are anticorrelated with the degree of industrialization. The normalized correlation coefficients are $c_{s\iota} = -0.85$ and $c_{f\iota} = -0.70$, where

$$c_{ab} = \frac{\langle ab \rangle_{(a,b)}}{\sqrt{\langle aa \rangle_{(a)} \langle bb \rangle_{(b)}}}.$$
(1)

Assume further that there is no direct correlation between f and s, i.e., $\mathcal{P}(s|f,\iota) = \mathcal{P}(s|\iota)$ and $\mathcal{P}(f|s,\iota) = \mathcal{P}(f|\iota)$. Derive an expression for $\langle sf \rangle_{(s,f,\iota)}$. Use this to calculate the normalized correlation coefficient c_{sf} (2 points).

Exercise 6-2

Given a field $s: S^2 \to \mathbb{C}$ on the two-dimensional sphere, assume that it is statistically homogeneous and isotropic, i.e., $S(\hat{n}, \hat{n}') = \langle s(\hat{n})s^*(\hat{n}') \rangle = S(\hat{n} \cdot \hat{n}')$, where \hat{n} and \hat{n}' are unit vectors that give directions or, equivalently, points on S^2 . Prove that the covariance matrix S is diagonal in the basis given by the spherical harmonic functions and its entries are independent of m, i.e.,

$$S_{(\ell m)(\ell' m')} := \langle s_{\ell m} s^*_{\ell' m'} \rangle = \delta_{\ell \ell'} \delta_{m m'} C_{\ell}.$$
(2)

(3 points)

<u>Hint</u>: Use the following properties of the spherical harmonic functions $Y_{\ell m}$ and the Legendre polynomials P_{ℓ} :

$$s(\hat{n}) = \sum_{\ell=0}^{\infty} \sum_{m=-\ell}^{\ell} s_{\ell m} Y_{\ell m}(\hat{n}), \qquad s_{\ell m} = \int_{\mathcal{S}^2} \mathrm{d}\Omega \; s(\hat{n}) Y_{\ell m}^*(\hat{n}) \tag{3}$$

$$\int_{\mathcal{S}^2} \mathrm{d}\Omega \; Y^*_{\ell m}(\hat{n}) Y_{\ell' m'}(\hat{n}) = \delta_{\ell\ell'} \delta_{mm'} \tag{4}$$

$$P_{\ell}(\hat{n} \cdot \hat{n}') = \frac{4\pi}{2\ell + 1} \sum_{m = -\ell}^{\ell} Y_{\ell m}^{*}(\hat{n}) Y_{\ell m}(\hat{n}')$$
(5)

Exercise 6-3

Imaging devices can probe continuous fields, such as physical flux or matter densities, by pixel averaged measurements. Assume the value d_i in the *i*th pixel of the obtained image satisfies

$$d_i = \int_{\Omega} \mathrm{d}x \ R_i(x)s(x) + n_i \qquad \text{with} \qquad i \in I = \{1, \dots, u\}, \tag{6}$$

where $R: I \times \Omega \to \mathbb{R}$ denotes the instrument response function, $s: \Omega \to \mathbb{R}$ the signal field, and $n \in \mathbb{R}^u$ the noise vector. Both, signal and noise, are a priori assumed to be independent of each other and to follow Gaussian distributions,

$$s \curvearrowleft \mathcal{G}(s-t,S)$$
 and $n \curvearrowleft \mathcal{G}(n-r,N),$ (7)

with known non-zero means, $t: \Omega \to \mathbb{R}$ and $r \in \mathbb{R}^{u}$, as well as known covariances, $S: \Omega \times \Omega \to \mathbb{R}$ and $N \in \mathcal{M}_{u \times u}(\mathbb{R})$.

- a) Derive an expression for the likelihood, P(d|s). Which quantity needs to be marginalized over? (1 point)
- b) Compute the full information Hamiltonian (including constant terms); i.e., $H(d, s) = -\log P(d, s)$. Identify the information propagator, D and the information source, j. (2 points)
- c) Derive an expression for the posterior mean field, $m = \langle s \rangle_{(s|d)}$, in terms of the given image, d. To do so use the maximum a posterior Ansatz. (2 points)
- d) Say the field \tilde{m} was inferred from a modified data set \tilde{d} applying a Wiener filter that solely uses S, R, and N. Given the following relation between the image data d and \tilde{d} ,

$$\widetilde{d}_i = d_i - \int_{\Omega} \mathrm{d}x \ R_i(x) t(x) - r_i; \tag{8}$$

Find the relation between the posterior mean field m derived in c) and the field \tilde{m} . (2 points)

https://www.mpa.mpa-garching.mpg.de/~ensslin/lectures/lectures.html

This exercise sheet will be discussed during the exercises. Group 01, Wednesday 18:00 - 20:00, Theresienstr. 37, A 449, Group 02, Thursday, 10:00 - 12:00, Theresienstr. 37, A 249,