Exercise sheet 7

Exercise 7-1

Exercise 7-2: Experimental constraints Consider the potential $V(\vec{r})$ which is symmetric with respect to the radial distance $r = |\vec{r}|$,

$$V(r) = a\sqrt{r} + b. \tag{1}$$

This potential is parametrized by the unknown numbers $a, b \in \mathbb{R}$ and can be measured at strictly positive radii, i.e., r > 0. Furthermore, only a single data point $d \in \mathbb{R}$ can be obtained,

$$d = V(r) + n, (2)$$

where the noise n is assumed to obey a Gaussian statistic $\mathcal{P}(n) = \mathcal{G}(n, N)$. The noise variance N = N(r), however, depends on the measurement position,

$$N(r) = r^2 + 3. (3)$$

a) Find an expression for the information entropy $S[\mathcal{P}(s|d)]$ for a Gaussian posterior

$$\mathcal{P}(s|d) = \mathcal{G}(s-m,D) , \qquad (4)$$

with mean m and covariance D (2 points).

- b) Consider the signal $s = \begin{pmatrix} a \\ b \end{pmatrix}$, for which a Gaussian prior $\mathcal{P}(s) = \mathcal{G}(s, 1)$ can be assumed. (2 points)
 - Write Eq. (2) in the form d = Rs + n and give R explicitly.
 - Work out an expression for the joint probability $\mathcal{P}(d,s)$ and calculate the corresponding Hamiltonian $H(d,s) = -\log \mathcal{P}(d,s) = \frac{1}{2}s^{\dagger}D^{-1}s j^{\dagger}s + H_0$. You may drop H_0 .
 - Identify the information source j and the inverse information propagator D^{-1} .
- c) You verified in a) that information entropy S = S(D) is a monotonically increasing function of |D|. Find the best position \tilde{r} to estimate both, a and b, by minimizing |D| from b) with respect to r (1 point).
- d) Now, consider the signal s = a for which b becomes a nuisance parameter. (1 point)
 - Work out an expression for the joint probability $\mathcal{P}(d, a)$, and calculate the corresponding Hamiltonian $H(d, a) = -\log \mathcal{P}(d, a) = \frac{1}{2}D^{-1}a^2 ja + H_0$. You may drop H_0 .
 - Identify the information source j and the information propagator D.
- e) Find the best position \tilde{r}_a to estimate *a* irrespectively of *b*, by minimizing *D* from d) with respect to *r* (1 point).
- f) Guess at which radius \tilde{r}_b one should measure in order to obtain the most certain estimate for the parameter b. No justification required (1 point).

Exercise 7-2

The goal of this exercise is to evaluate the integral

$$I(x) = \int_{-\infty}^{\infty} \mathrm{d}k \frac{e^{-ikx}}{k^2 + m^2} \tag{5}$$

- a) For $k \in \mathbb{C}$, the integrand can diverge. Identify the poles of the integrand and sketch them in the complex plane, sketch the integration path of $k \in (-\infty, \infty)$ as well (2 points).
- b) Draw a contour line that closes the integral, connecting $k = \infty$ to $k = -\infty$. The integral of the added contour line should be 0. Illustrate why it is 0 by comparing orders in k (2 points).

<u>Hint</u>: You may assume x > 0.

c) The closed integral encloses one pole. Identify its order and evaluate the integral I(x) using the residue theorem,

$$\int_{\Gamma} f = (2\pi i) \sum_{a \in R_f} \operatorname{ind}_{\Gamma}(a) \operatorname{Res}_a f, \tag{6}$$

where Γ is a closed contour, R_f are the poles of f, and $\operatorname{ind}_{\Gamma}(a)$ is the number of counter-clockwise windings of Γ around a, and the residue formula,

$$\operatorname{Res}_{a} f = \frac{1}{(n-1)!} \lim_{z \to a} \frac{\partial^{n-1}}{\partial z^{n-1}} \left[(z-a)^{n} f(z) \right],$$
(7)

where n is the order of the pole a (2 points).

Hint: A clockwise winding is a negative counter-clockwise winding.

This exercise sheet will be discussed during the exercises.

group A, Wednesday 16:00 - 18:00 Theresienstr. 39 - room B 101,

group B, Thursday, 10:00 - 12:00, Geschw.-Scholl-Pl. 1 (B) - room B 015

group C, Thursday, 16:00 - 18:00, Theresienstr. 37 - room A 449

backup slot, Wednesday, 8:00 - 10:00, Theresienstr. 37 - A 450

⁽to be used whenever Thursday is a vacation day)

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