

Exercise sheet 7

Exercise 7 - 1

You are observing a region of the sky with a photodetector. On average a number of photons λ makes it's way from the sky into your detector per time interval.

Hint: The PDF for n photon counts per time interval is given by the Poisson distribution:

$$\mathcal{P}(n|\lambda) = \frac{\lambda^n e^{-\lambda}}{n!}$$

a) Calculate the expectation value and the standard deviation for the photon counts per time interval (3 Points).

b) Use the PDF to calculate the expectation value $\langle \frac{n!}{(n-q)!} \theta(n-q) \rangle_{(n|\lambda)}$ with

$$\theta(x) = \begin{cases} 1 & \text{for } x \geq 0 \\ 0 & \text{else} \end{cases} \quad (1)$$

for any $q \in \{0, 1, \dots, n\}$, where n denotes the photon counts per time interval (2 Points).

Exercise 7 - 2

The goal of this exercise is to evaluate the integral

$$I(x) = \int_{-\infty}^{\infty} dk \frac{e^{-ikx}}{k^2 + m^2} \quad (2)$$

a) For $k \in \mathbb{C}$, the integrand can diverge. Identify the poles of the integrand and sketch them in the complex plane, sketch the integration path of $k \in (-\infty, \infty)$ as well (2 points).

b) Draw a contour line that closes the integral, connecting $k = \infty$ to $k = -\infty$. The integral of the added contour line should be 0. Illustrate why it is 0 by comparing orders in k (2 points).

Hint: You may assume $x > 0$.

c) The closed integral encloses one pole. Identify its order and evaluate the integral $I(x)$ using the residue theorem,

$$\int_{\Gamma} f = (2\pi i) \sum_{a \in R_f} \text{ind}_{\Gamma}(a) \text{Res}_a f, \quad (3)$$

where Γ is a closed contour, R_f are the poles of f , and $\text{ind}_{\Gamma}(a)$ is the number of counter-clockwise windings of Γ around a , and the residue formula,

$$\text{Res}_a f = \frac{1}{(n-1)!} \lim_{z \rightarrow a} \frac{\partial^{n-1}}{\partial z^{n-1}} [(z-a)^n f(z)], \quad (4)$$

where n is the order of the pole a (2 points).

Hint: A clockwise winding is a negative counter-clockwise winding.

Exercise 7 - 3

A signal $s : \mathbb{R}^u \rightarrow \mathbb{R}$ with Gaussian statistics and known covariance $S = \langle ss^\dagger \rangle_{(s)}$ is measured via $d_x = s_x + n_x$. The noise follows Gaussian statistics and is homogeneous except for a slight enhancement in an area Ω , i.e., $N_{xy} = \langle n_x n_y \rangle_{(n)} = \delta(x-y) (1 + \epsilon \Theta_{\Omega}(x)) \sigma^2$. Here, $\Theta_{\Omega}(x) = 1$ for $x \in \Omega$ and $\Theta_{\Omega}(x) = 0$ for $x \notin \Omega$. Consider the Wiener filter for this inference problem.

- a) Calculate perturbatively to first order in ϵ the effect of the noise inhomogeneity on the real-space structure of the propagator (3 points).

Hint: The following relation for the differentiation of a regular matrix A depending on a parameter p might be useful:

$$\begin{aligned}\frac{\partial}{\partial p} (A^{-1}A) &= 0 \\ \Leftrightarrow 0 &= \frac{\partial A^{-1}}{\partial p} A + A^{-1} \frac{\partial A}{\partial p} \\ \Leftrightarrow \frac{\partial A^{-1}}{\partial p} &= -A^{-1} \frac{\partial A}{\partial p} A^{-1}\end{aligned}$$

- b) Calculate N in its Fourier representation for general Ω and for $\Omega = [-L, L]$ in the one-dimensional case (3 points).

This exercise sheet will be discussed during the exercises.

Group 01, Wednesday 18:00 - 20:00, Theresienstr. 37, A 449,

Group 02, Thursday, 10:00 - 12:00, Theresienstr. 37, A 249,

<https://wwwmpa.mpa-garching.mpg.de/ensslin/lectures/lectures.html>